

MVMYC Pond (Deer Meadow Park) Moraine, Ohio ArduPilot Mission Planner Way Points

ArduPilot Mission Planner Simulation incorporates Google Map and includes two user generated files.

Way Points C:\Program Files (x86)\Mission Planner\WayPointsDemo.waypoints

Way Points = Green Circle with Numbers

Launch Point = Green Circle with "H"

Points of Interest (not shown in this view)

Other numerous simulation and sailboat parameters are stored at

C:\Program Files (x86)\Mission Planner\DMKArduParameters.param

including *Wind Direction & Speed* and the tacking criteria *Maximum_Cross_Track_Error*

Note: Way Points are guidance positions for steering and would need to be offset from race course marker buoys.

